

Accurate Rectangular Window Subspace Tracking

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• Given a sequence of column vectors \mathbf{x}_t , we can define the $n \times c$ overlapping matrices, M_{old} and \tilde{M}_{new} , along with their SVDs, as

$$M_{old} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \cdots & \mathbf{x}_c \end{bmatrix} = U_{old} \Sigma_{old} V_{old}^H$$
$$\tilde{M}_{new} = \begin{bmatrix} \mathbf{x}_2 & \cdots & \mathbf{x}_c & \mathbf{x}_{c+1} \end{bmatrix} = \tilde{U}_{new} \tilde{\Sigma}_{new} \tilde{V}_{new}^H$$

- Using the rank-two secular function, we can determine the singular values and left singular vectors of \tilde{M}_{new} from the singular values and left singular vectors of M_{old} with one $O(n^3)$ matrix product
- Using the IFAST algorithm, we can determine an approximation to the r largest singular values and left singular vectors of \tilde{M}_{new} from the r largest singular values and left singular vectors of M_{old} with one $O(nr^2)$ and two $O(r^3)$ matrix products



- M_{old} , $\tilde{M}_{new} \in \mathbb{C}^{32 \times 32}$
- Similar plot for other matrix dimensions.
- The full decomposition and the secular update produce identical results.
- Offset in IFAST at r = 0comes from O(nc) terms.



- For large r, the dominant term in the IFAST computation is an $r+2 \times r+2$ eigendecomposition.
- All methods calculate singular values and left singular vectors only.



 $\bullet\,$ If we define the two vectors ${\bf a}$ and ${\bf b},$

$$\mathbf{a} = U_{old}^H \mathbf{x}_1, \qquad \mathbf{b} = U_{old}^H \mathbf{x}_{c+1}$$

then we can define the matrix $ilde{G}$ as

$$\tilde{G} = U_{old}^H \tilde{M}_{new} \tilde{M}_{new}^H U_{old} = \Sigma_{old}^2 - \mathbf{a}\mathbf{a}^H + \mathbf{b}\mathbf{b}^H$$

which is a diagonal matrix plus two rank one matrices.

• If we write the eigendecomposition of \tilde{G} as

$$\tilde{G} = \tilde{U}_G \tilde{\Sigma}_G \tilde{U}_G^H$$

then the singular values and left singular vectors of \tilde{M}_{new} are

$$ilde{\Sigma}_{new} = \sqrt{ ilde{\Sigma}_G}$$
 and $ilde{U}_{new} = U_{old} ilde{U}_G$



• The eigenvalues of \tilde{G} are the roots of the rank-two secular equation

$$w(\lambda) = \left(1 - \sum_{j=1}^{n} \frac{|a_j|^2}{\sigma_j^2 - \lambda}\right) \left(1 + \sum_{j=1}^{n} \frac{|\mathbf{b}_j|^2}{\sigma_j^2 - \lambda}\right) + \left|\sum_{j=1}^{n} \frac{a_j^* \mathbf{b}_j}{\sigma_j^2 - \lambda}\right|^2$$
$$w(\lambda) = w_a(\lambda) w_{\mathbf{b}}(\lambda) + |w_{a\mathbf{b}}(\lambda)|^2$$

where $w_a(\lambda)$ is the secular function for $\Sigma_{old}^2 - \mathbf{a}\mathbf{a}^H$, and $w_b(\lambda)$ is the secular function for $\Sigma_{old}^2 + \mathbf{b}\mathbf{b}^H$

• The unnormalized *i*th eigenvector of \tilde{G} is

$$\frac{\tilde{\mathbf{u}}_i}{c_s} = \left(\Sigma_{old}^2 - \tilde{\sigma}_i^2 I\right)^{-1} \left(\mathbf{a} + \frac{w_a(\tilde{\sigma}_i^2)}{w_{ab}(\tilde{\sigma}_i^2)} \mathbf{b}\right)$$



Rank-Two Secular Function



Poles of $w(\lambda)$ are squares of singular values of M_{old} Roots of $w(\lambda)$ and $C(\lambda)$ are squares of singular values of \tilde{M}_{new} Note that each new eigenvalue is bounded by $\sigma_{i+1}^2 < \tilde{\sigma}_i^2 < \sigma_{i-1}^2$



- M_{old} shares all but one column with \tilde{M}_{new} , therefore U'_{old} is a reasonable approximation to the columnspace of \tilde{U}'_{new} , except for the contribution of \mathbf{x}_1 and \mathbf{x}_{c+1}
- If we define q_1 and q_2 as a Gram-Schmidt augmentation to U'_{old} ,

$$\mathbf{z}_{1} = (I - U'_{old} U'_{old}^{H}) \mathbf{x}_{c+1}, \qquad \mathbf{q}_{1} = \mathbf{z}_{1} / \|\mathbf{z}_{1}\|, \\ \mathbf{z}_{2} = (I - [U'_{old} | \mathbf{q}_{1}] [U'_{old} | \mathbf{q}_{1}]^{H}) \mathbf{x}_{1}, \qquad \mathbf{q}_{2} = \mathbf{z}_{2} / \|\mathbf{z}_{2}\|,$$

then we can define

$$\tilde{M}'_{new} = [U'_{old} \mid Q] [U'_{old} \mid Q]^H \tilde{M}_{new}$$

The *r* largest singular values and left singular vectors of the rank r + 2 matrix \tilde{M}'_{new} , are reasonable approximations to the *r* largest singular values and left singular vectors of \tilde{M}_{new}

• Substituting \tilde{M}'_{new} for \tilde{M}_{new} is the only approximation in IFAST



| Step | | Description |
|------|--|--|
| 1) | $\begin{aligned} \mathbf{z}_{1} &= \left(I - U_{old}^{\prime} U_{old}^{\prime H}\right) \mathbf{x}_{c+1} \\ \mathbf{q}_{1} &= \mathbf{z}_{1} / \ \mathbf{z}_{1}\ \\ \mathbf{z}_{2} &= \left(I - \left[U_{old}^{\prime} \mid \mathbf{q}_{1}\right] \left[U_{old}^{\prime} \mid \mathbf{q}_{1}\right]^{H}\right) \mathbf{x}_{1} \\ \mathbf{q}_{2} &= \mathbf{z}_{2} / \ \mathbf{z}_{2}\ \end{aligned}$ | Gram-Schmidt augment U'_{old} with the column we are dis- carding, \mathbf{x}_1 , and the column we are adding, \mathbf{x}_{c+1} , to create the matrix $Q = [\mathbf{q}_1 \ \mathbf{q}_2]$, where $[U'_{old} Q]^H [U'_{old} Q] = I$ |
| 2) | $\begin{split} \tilde{D} &= \Sigma_{old}^{\prime 2} - U_{old}^{\prime H} \mathbf{x}_{1} \mathbf{x}_{1}^{H} U_{old}^{\prime} + U_{old}^{\prime H} \mathbf{x}_{c+1} \mathbf{x}_{c+1}^{H} U_{old}^{\prime} \\ \tilde{F} &= \begin{bmatrix} \tilde{D} & U_{old}^{\prime H} \tilde{M}_{new} \tilde{M}_{new}^{H} Q \\ \hline Q^{H} \tilde{M}_{new} \tilde{M}_{new}^{H} U_{old}^{\prime} & Q^{H} \tilde{M}_{new} \tilde{M}_{new}^{H} Q \end{bmatrix} \end{split}$ | Create \tilde{F} , whose eigendecomposition will give us the SVD of \tilde{M}'_{new} . Equivalent to $\tilde{F} = [U'_{old} Q]^H \tilde{M}_{new} \tilde{M}^H_{new} [U'_{old} Q]$ |
| 3) | $\tilde{U}_f \tilde{\Sigma}_f \tilde{U}_f^H = \tilde{F}$ | Take eigendecomposition of $	ilde{F}$ |
| 4) | $ \begin{split} \tilde{U}_{new}' &= \begin{bmatrix} U_{old}' \mid Q \end{bmatrix} \tilde{U}_{f} \\ \tilde{\Sigma}_{new}'^{2} &= \tilde{\Sigma}_{f} \end{split} $ | Determine the singular values and left singular vectors of \tilde{M}'_{new} |



IFAST Performance





- Given $U_{\!old}$ and Σ_{old} from M_{old} , and defining like before

 $\mathbf{a} = U_{old}^{H} \mathbf{x}_{1}, \qquad \mathbf{b} = U_{old}^{H} \mathbf{x}_{c+1}$ the matrix $\tilde{G} = U_{old}^{H} \tilde{M}_{new} \tilde{M}_{new}^{H} U_{old}$, can be written as $\tilde{G} = \Sigma_{old}^{2} - \mathbf{a}\mathbf{a}^{H} + \mathbf{b}\mathbf{b}^{H}$

• Given U'_{old} and Σ'_{old} from M_{old} , and defining $\hat{\Sigma} = Q^H M_{old} M_{old}{}^H Q$, $\hat{\mathbf{a}} = Q^H \mathbf{x}_1$, $\hat{\mathbf{b}} = Q^H \mathbf{x}_{c+1}$ the matrix $\tilde{F} = [U'_{old} Q]^H \tilde{M}_{new} \tilde{M}^H_{new} [U'_{old} Q]$, can be written as

$$\tilde{F} = \begin{bmatrix} \frac{\Sigma_{old}^{\prime 2} \mid 0}{0 \mid \hat{\Sigma}} \end{bmatrix} - \begin{bmatrix} \frac{\mathbf{a}^{\prime}}{\hat{\mathbf{a}}} \end{bmatrix} \begin{bmatrix} \frac{\mathbf{a}^{\prime}}{\hat{\mathbf{a}}} \end{bmatrix}^{H} + \begin{bmatrix} \frac{\mathbf{b}^{\prime}}{\hat{\mathbf{b}}} \end{bmatrix} \begin{bmatrix} \frac{\mathbf{b}^{\prime}}{\hat{\mathbf{b}}} \end{bmatrix}^{H}$$

• We can now use their rank-two secular functions for comparison



Comparison of Secular Functions





- The rank-two secular function is the product of the two rank-one secular functions plus a cross term, $w(\lambda) = w_a(\lambda)w_b(\lambda) + |w_{ab}(\lambda)|^2$
- We can define the difference of the rank one secular function of $\tilde{G}_b = \Sigma_{old}^2 + \mathbf{bb}^H$ and \tilde{F}_b as

$$e_{f_b}(\lambda) = w_{f_b}(\lambda) - w_{g_b}(\lambda)$$

and the unique parts of $w_{\textit{f}_{\textit{b}}}(\lambda)$ and $w_{\textit{g}_{\textit{b}}}(\lambda)$ as

$$u_{\underline{g}_{b}}(\lambda) = -\sum_{j=r+1}^{n} \frac{|\underline{b}_{j}|^{2}}{\lambda} \sum_{i=2}^{\infty} \left(\frac{\sigma_{j}^{2}}{\lambda}\right)^{i}, \qquad u_{\underline{f}_{b}}(\lambda) = -\sum_{j=1}^{2} \frac{|\hat{\underline{b}}_{j}|^{2}}{\lambda} \sum_{i=2}^{\infty} \left(\frac{\hat{\sigma}_{j}}{\lambda}\right)^{i}$$

The three functions e_{fb}(λ), u_{gb}(λ), and u_{fb}(λ) are all about the same magnitude in the region of λ that we are interested in, therefore u_{fb}(λ) can be used to give an idea of the error in the approximation







- IFAST Algorithm Singular value and left singular vector estimates in $O(nr^2)$ time. Improved the computational efficiency, accuracy, and flexibility of the FAST algorithm.
- Secular Method Method to find eigendecomposition of a diagonal matrix plus two rank one matrices in $O(n^2)$ time, and update the singular values and left singular vectors of a matrix where one column changes with a single $O(n^3)$ matrix product.
- IFAST Analysis Show how to use rank-two secular function to analyze accuracy of IFAST algorithm. This gives some insight into where IFAST is applicable.